CS 181 Spring 2021 Section 6: SVM Dual + Kernels

1 SVM Review

Support Vector Machines (SVMs) learn a decision boundary for binary classification problems using weight vector \mathbf{w} and bias w_0 . For some point \mathbf{x} , the boundary is defined by:

$$\mathbf{w}^{\top}\mathbf{x} + w_0 = 0$$

Given a setting of \mathbf{w}, w_0 , we make a prediction on \mathbf{x} by computing the discriminant function:

$$h(\mathbf{x}, \mathbf{w}, w_0) = \mathbf{w}^\top \mathbf{x} + w_0$$

and classify \mathbf{x} as y = 1 if h > 0 and y = -1 otherwise. How good is our SVM? Of all the ways to cleanly separate the two classes when possible, we should pick a boundary that is furthest away from the closest points to the boundary! The signed orthogonal distance of \mathbf{x} from boundary:

$$r(\mathbf{x}) = \frac{\mathbf{w}^{\top} \mathbf{x} + w_0}{||\mathbf{w}||}$$

When points are classified correctly, this is negative for points i with $y_i = -1$ and positive for those with $y_i = 1$. Then margin of the model is the smallest (over datapoints) *unsigned* distance. Multiply with y_i to get rid of signs:

$$\operatorname{margin}(\mathbf{w}, w_0) = \min_i y_i r(\mathbf{x}_i) = \min_i \frac{y_i(\mathbf{w}^\top \mathbf{x} + w_0)}{||\mathbf{w}||} \quad \text{(want this to be large)}$$

The SVM objective is to maximize the margin (which itself is defined as a min over points!)! The $\frac{1}{||\mathbf{w}||}$ term can come out of the min_i since it doesn't depend on *i*. The objective to maximize is:

$$\max_{\mathbf{w},w_0} \frac{1}{||\mathbf{w}||} \min_i y_i \Big[\mathbf{w}^\top \mathbf{x}_i + w_0 \Big]$$

In this hard-margin formulation (soft-margin out of scope for these notes), if the data is truly linearly separable than the margin satisfies:

$$\operatorname{margin}(\mathbf{w}, w_0) = \min_i y_i r(\mathbf{x}_i) > 0.$$

Assuming data is separable, then the margin is some positive number. We can rescale \mathbf{w}, w_0 so that this positive margin is specifically 1 or greater without changing the orientation of the boundary. Then the boundary satisfies:

$$\operatorname{margin}(\mathbf{w}, w_0) = \min y_i r(\mathbf{x}_i) > 1$$

Let's re-write the objective to make this constraint explicit (don't need to know how to justify to these re-writes, but see optimization theory if interested e.g. Stanford prof Boyd's videos on YouTube):

$$\max_{\mathbf{w}, w_0} \frac{1}{||\mathbf{w}||} \quad \text{s.t.} \quad \forall i, y_i(\mathbf{w}^\top \mathbf{x}_i + w_0) \ge 1$$

where s.t. stands for "such that" and \forall_i means "for all *i*". A different-looking objective with the same solution is (**w** in numerator instead of denom):

$$\min_{\mathbf{w},w_0} \frac{1}{2} ||\mathbf{w}||^2 \quad \text{s.t.} \quad \forall i, y_i(\mathbf{w}^\top \mathbf{x}_i + w_0) \ge 1$$

We will shortly see why the min-rewrite is useful. With either of the last two objectives, we say they are "quadratic problems with linear constraints" which means they can be solved easily!

2 Dual Formulation of SVMs

We will now show an alternate view on the SVM problem. It will reveal an algorithm that look something analogous to KNN for regression. This new way of looking at SVMs will highlight some convenient ways of dealing with high-dimensional data! We left off with this loss function with constraints:

$$\min_{\mathbf{w}, w_0} \frac{1}{2} ||\mathbf{w}||^2 \quad \text{s.t.} \quad \forall i, y_i(\mathbf{w}^\top \mathbf{x}_i + w_0) \ge 1$$

We use an idea called the Lagrangian (see optimization theory) to re-write this constrained objective so that some of the constraints end up in the main function to be optimized. We introduce *lagrange multipliers* a_i for each constraint (we have one for every datapoint) similarly to how you used λ in HW2 to write $\sum_k \pi_k = 1$ as $\lambda \left(\sum_k \pi_k - 1 \right)$

$$\min_{\mathbf{w},w_0} \left[\max_{a_i} \left(\frac{1}{2} \mathbf{w}^\top \mathbf{w} - \sum_i a_i \left[y_i (\mathbf{w}^\top \mathbf{x}_i + w_0) - 1 \right] \right) \right] \quad \text{s.t.} \quad a_i \ge 0$$

where we also used that $||\mathbf{w}||^2 = \mathbf{w}^\top \mathbf{w}$. Having changed the max to a min in the previous section and then applying the Lagrangian trick, we are left with a "min-max" problem that is quadratic with linear constraints. Beautifully/interestingly, some optimization theory tells us this can (finally) be re-written as:

$$\max_{a_i} \sum_i a_i - \frac{1}{2} \sum_i \sum_j a_i a_j y_i y_j (\mathbf{x}_i^\top \mathbf{x}_j) \quad \text{s.t.} \quad a_i \ge 0, \sum_i a_i y_i = 0$$

This has no **w** or w_0 ! Just a constrained optimization problem in terms of the a_i . We call the set of points $\{\mathbf{x}_i | a_i > 0\}$. the **support vectors** since they contribute to the objective value at its optimum.

How do we predict without \mathbf{w}, w_0 ? Hidden in the last step that removed \mathbf{w}, w_0 from the objective was the condition that $\mathbf{w} = \sum_i a_i y_i \mathbf{x}_i$. Hidden also was a condition that tells us to find any i with $a_i > 0$ and to set $w_0 = y_i \mathbf{w}^\top \mathbf{x}_i$. For a concise explanation see the cs181 SVM 2 lecture recap or David Sontag's MIT notes. Then our discriminant can be written as

$$h(\mathbf{x}, w, w_0) = \mathbf{w}^{\top} \mathbf{x} + w_0$$

$$\implies h(\mathbf{x}, a, w_0) = \sum_i a_i y_i(\mathbf{x}_i^{\top} \mathbf{x}) + w_0$$

That is, to predict, we take dot products of the test point \mathbf{x} with the dataset support vectors i.e. the set of \mathbf{x}_i with $a_i > 0$. Qualitatively, this is like KNN: the complexity of prediction depends on the data rather than a fixed parameter vector. However, when the number of support vectors is small relative to the data dimension, this is cheap!

3 Basis Functions, Higher Dimensions, and Kernels

Suppose the data were not separable as-is but were separable using some basis ϕ . Lets just replace any **x** with $\phi(\mathbf{x})$ in the final objective:

$$\max_{a_i} \sum_{i} a_i - \frac{1}{2} \sum_{i} \sum_{j} a_i a_j y_i y_j \left(\phi(\mathbf{x}_i)^\top \phi(\mathbf{x}_j) \right) \quad \text{s.t.} \quad a_i \ge 0, \sum_{i} a_i y_i = 0$$

and in the discriminant function:

$$h(\mathbf{x}, a, w_0) = \sum_{i} a_i y_i \left(\phi(\mathbf{x}_i)^\top \phi(\mathbf{x}) \right) + w_0$$

Suppose we needed to use a fairly high-dimensional basis function to achieve separability e.g. mapping to all powers up to 100. Well, notice that we don't explicitly need the values of each $\phi(\mathbf{x}_i)$ or $\phi(\mathbf{x})$ but we only need to know the result of the dot product of basis vectors on pairs. Then, we can directly define the **kernel function** for two vectors \mathbf{x}, \mathbf{z}

$$K(\mathbf{x}, \mathbf{z}) = \phi(\mathbf{x})^\top \phi(\mathbf{z})$$

We can pick K such that we can compute it without ever computing an individual $\phi(\mathbf{x})$. For example, let's take

$$K(\mathbf{x}, \mathbf{z}) = (\mathbf{x}^{\top} \mathbf{z})^3$$

Example: Poly Kernels Lets consider $\mathbf{x} \in \mathbb{R}^2$ and see how we would represent this as a basis dot product. Write $K(\mathbf{x}, \mathbf{z}) = (\mathbf{x}^\top \mathbf{z})^3 = (x_1 z_1 + x_2 z_2)^3$ as a dot-product $\phi(\mathbf{x})^\top \phi(\mathbf{z})$. How is $\phi()$ defined?

$$\begin{aligned} (\mathbf{x}^{\top}\mathbf{z})^{3} &= (x_{1}z_{1} + x_{2}z_{2})^{3} \\ &= (x_{1}z_{1} + x_{2}z_{2})(x_{1}z_{1} + x_{2}z_{2})(x_{1}z_{1} + x_{2}z_{2}) \\ &= \left(x_{1}^{2}z_{1}^{2} + 2x_{1}z_{1}x_{2}z_{2} + x_{2}^{2}z_{2}^{2}\right)(x_{1}z_{1} + x_{2}z_{2}) \\ &= x_{1}^{2}z_{1}^{2}(x_{1}z_{1} + x_{2}z_{2}) + 2x_{1}z_{1}x_{2}z_{2}(x_{1}z_{1} + x_{2}z_{2}) + x_{2}^{2}z_{2}^{2}(x_{1}z_{1} + x_{2}z_{2}) \\ &= x_{1}^{3}z_{1}^{3} + x_{2}^{3}z_{2}^{3}3x_{1}^{2}z_{1}^{2}x_{2}z_{2} + 3x_{2}^{2}z_{2}^{2}x_{1}z_{1} \\ &= \left(x_{1}^{3}, x_{2}^{3}, 3x_{1}^{2}x_{2}, 3x_{2}^{2}x_{1}\right)^{\top} \left(z_{1}^{3}, z_{2}^{3}, 3z_{1}^{2}z_{2}, 3z_{2}^{2}z_{1}\right) \end{aligned}$$

which implies the basis $\phi(\mathbf{x}) = [x_1^3, x_2^3, 3x_1^2x_2, 3x_2^2x_1]$. But we only picked $\mathbf{x} \in \mathbb{R}^2$ and a degree 3 basis. More generally if the data dimension is D and degree is q we have $O(D^q)$ terms! But if we just compute the function K we don't first need to map to these high-dimensional bases. Put another way, we can pick functions K that imply the use of very high-dim bases!

3.1 What's a valid kernel?

When training SVMs, we begin by computing the kernel matrix **K**, over our training data $\{\mathbf{x}_1, \ldots, \mathbf{x}_n\}$. The kernel matrix $\mathbf{K} \in \mathbb{R}^{n \times n}$, defined as $K_{i,j} = K(\mathbf{x}_i, \mathbf{x}_j)$, expresses the kernel function applied between all pairs of training points.

Mercer's theorem tells us that any function K that yields a **positive** semi-definite kernel matrix forms a valid kernel, that is, corresponds to a matrix of dot-products under *some* basis ϕ . Recall that a positive semi-definite matrix \mathbf{K} requires $\mathbf{z}^{\top}\mathbf{K}\mathbf{z} \geq 0$, $\forall \mathbf{z} \in \mathbb{R}^n$. Therefore instead of using an explicit basis, we can build kernel functions directly that fulfill this property.

Example: Scaling to make a new kernel Suppose K is a valid kernel. Show that $K^{\text{new}}(\mathbf{x}, \mathbf{x}') = cK(\mathbf{x}, \mathbf{x}')$ for c > 0 is also a valid kernel. You can either show the positive semi-definite property or explicitly construct the basis.

We have the kernel matrix $\mathbf{K}^{\text{new}} = c\mathbf{K}$. We need $\mathbf{v}^{\top}\mathbf{K}^{\text{new}}\mathbf{v} = c\mathbf{v}^{\top}\mathbf{K}\mathbf{v} \ge 0$, which we know to be true because \mathbf{K} is positive semi-definite and c > 0. Alternatively, take $\phi^{\text{new}}(\mathbf{x}) = \sqrt{c} \phi(\mathbf{x})$.

4 Some more exercises

Exercise: Large Bases with Exp Suppose $x \in \mathbb{R}$ and suppose we pick $K(x, x') = \exp(xx')$ where $\exp(z) = e^z$. If we re-write $K(x, x') = \phi(x)^{\top} \phi(x')$ then how is the implied ϕ defined for this choice of K and what is the dimension of $\phi(x)$? *hint:* use

$$e^z = \lim_{i \to \infty} 1 + z + \ldots + \frac{z^i}{i!}$$

Exercise: String Kernels

Let **s** and **s'** be strings. To measure how similar **s** and **s'** are, consider the "string kernel" $K(\mathbf{s}, \mathbf{s'})$, which returns the total number of distinct substrings (of any length) that **s** and **s'** have in common. For example, $K(\mathsf{'aa'}, \mathsf{'aab'}) = 3$ because the substrings '', 'a', and 'aa' are in common.

- 1. Compute K('aza', 'zaz').
- 2. What is the number of possible substrings of length 1, 2, and 3 in strings that are composed from a 26-letter alphabet?
- 3. Suppose we wanted to project a string into a higher-dimensional space such that we could represent via a 0 or 1 each of all possible substrings of length \leq 3. How many dimensions would we need?
- 4. How does directly defining this string kernel help over computing the basis functions? Is it possible to compute the kernel itself efficiently?

Exercise: Composing Kernels

A particularly nice corollary of Mercer's theorem is that it allows us to build more expressive kernels by composition. We already saw that positive scaling yields a new kernel. Now, use Mercer's theorem and the definition of a kernel matrix to prove that the following compositions are valid kernels, assuming $K^{(1)}$ and $K^{(2)}$ are valid kernels.

[Note: It suffices to show that a kernel is valid either by finding a particular $\phi(\mathbf{x})$ that produces it, or by showing that the kernel matrix is positive semidefinite. Recall that a positive semi-definite matrix \mathbf{K} requires $\mathbf{z}^{\top}\mathbf{K}\mathbf{z} \geq 0, \forall \mathbf{z} \in \mathbb{R}^{n}$.]

- 1. $K(\mathbf{x}, \mathbf{x}') = K^{(1)}(\mathbf{x}, \mathbf{x}') + K^{(2)}(\mathbf{x}, \mathbf{x}')$
- 2. $K(\mathbf{x}, \mathbf{x}') = f(\mathbf{x}) K^{(1)}(\mathbf{x}, \mathbf{x}') f(\mathbf{x}')$ where $f : \mathbb{R}^m$ to \mathbb{R}
- 3. $K(\mathbf{x}, \mathbf{x}') = K^{(1)}(\mathbf{x}, \mathbf{x}') K^{(2)}(\mathbf{x}, \mathbf{x}')$

[Hint: Use the property that for any $\phi(\mathbf{x})$, $K(\mathbf{x}, \mathbf{x}') = \phi(\mathbf{x})^{\top} \phi(\mathbf{x}')$ forms a positive semi-definite kernel matrix.]

- 4. $K(\mathbf{x}, \mathbf{x}') = \exp\left(K^{(1)}(\mathbf{x}, \mathbf{x}')\right)$
- 5. Finally use this analysis and previous identities to prove the validity of the Gaussian kernel:

$$K(\mathbf{x}, \mathbf{x}') = \exp\left(\frac{-||\mathbf{x} - \mathbf{x}'||_2^2}{2\sigma^2}\right)$$