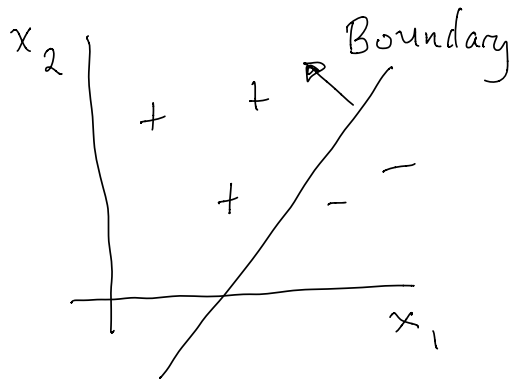


CS 181

Linear Classification



$$D = \{ (\underline{x}_1, y_1), \dots, (\underline{x}_n, y_n) \}$$

$$\underline{x}_n \in \mathbb{R}^D$$

$$y_n \in \{+1, -1\}$$

Goal: predict \hat{y} , on a new example \underline{x}

Method 1 Non-parametric

k-Nearest Neighbor

kernel methods

↳ majority vote on the k-NNs

⊕ flexible

⊗ Slow on big data sets

⊗ Not interpretable

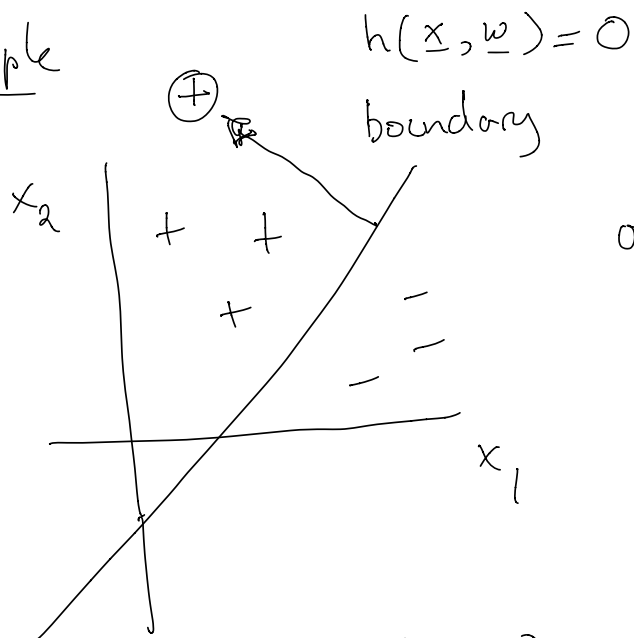
Method 2 Linear classification

discriminant function

$$h(\underline{x}, \underline{w}) = \underline{w}^T \underline{x} + w_0$$

predict $\hat{y} = \begin{cases} +1 & \text{if } h(\underline{x}, \underline{w}) > 0 \\ -1 & \text{otherwise} \end{cases}$

Example



orthogonal vector

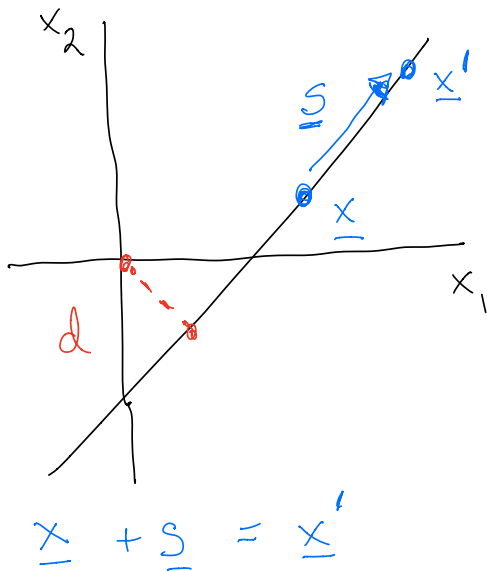
$$\underline{w} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$h(\underline{x}, \underline{w}) = -x_1 + x_2 + 1$$

Understanding boundary

Generally, hyperplane

$$S = \{ \underline{x} : \underline{w}^T \underline{x} + w_0 = 0 \}$$



$$\begin{aligned} \underline{w}^T \underline{s} &= \underline{w}^T \underline{x}' - \underline{w}^T \underline{x} \\ &= (\underline{w}^T \underline{x}' + w_0) - (\underline{w}^T \underline{x} + w_0) \\ &= 0 - 0 = 0 \end{aligned}$$

So, \underline{w} is orthogonal to the boundary.

\hookrightarrow \underline{w} sets the orientation.

d as the unsigned orthogonal distance between boundary + origin

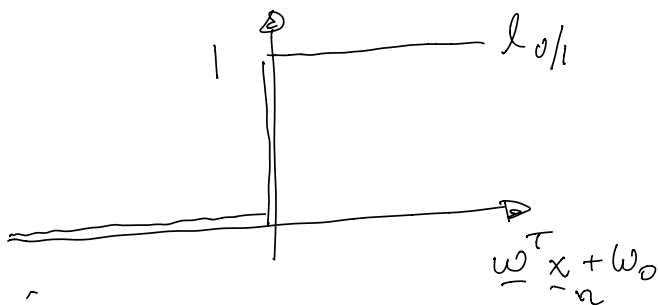
$$d = \frac{|w_0|}{\|\underline{w}\|_2}$$

\hookrightarrow w_0 sets the distance to the origin

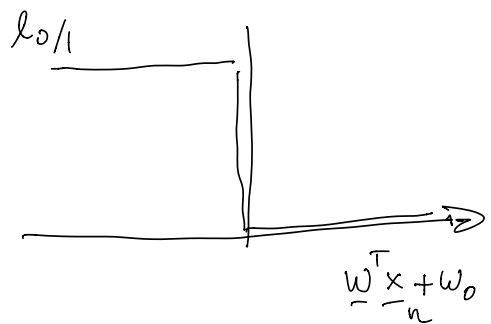
0/1 Loss function

Recall $\hat{y} = \begin{cases} +1 & \text{if } \underline{w}^T x + w_0 > 0 \\ -1 & \text{otherwise} \end{cases}$

For a negative example
(x_n, y_n)



For a positive
example



Define

$$l_{0/1}(z) = \begin{cases} 1 & \text{if } z > 0 \\ 0 & \text{otherwise} \end{cases}$$

$$L_D(\underline{w}) = \sum_n l_{0/1}(-y_n(\underline{w}^T x_n + w_0)) = \sum_{n: y_n \neq \hat{y}_n} 1$$

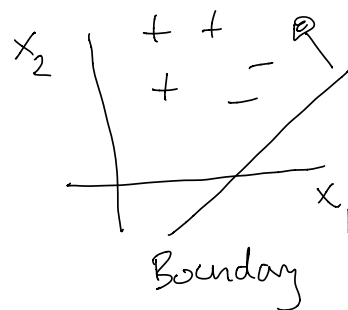
↳ scales with # mistakes

Problem

Want to use gradient descent

$$\underline{w}_{t+1} \leftarrow \underline{w}_t - \eta \frac{\partial L(\underline{w})}{\partial \underline{w}}$$

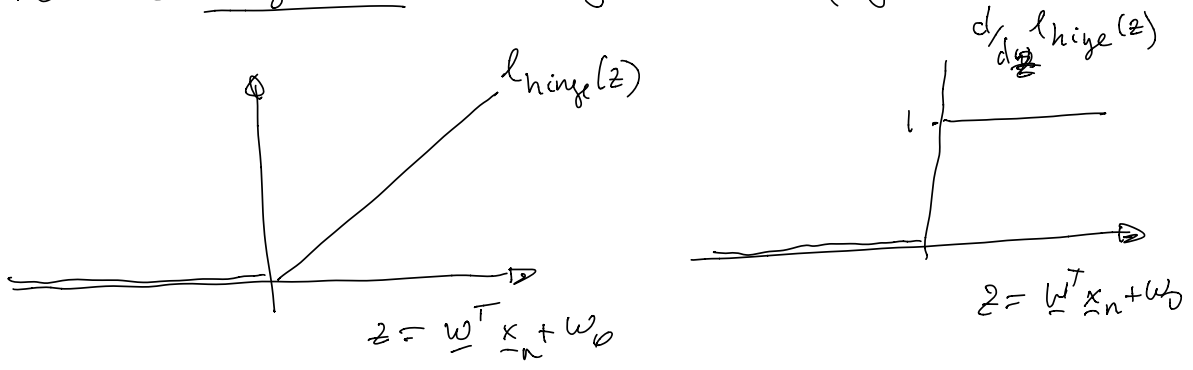
η step size (> 0)



But, gradients of $\mathcal{O}(1)$ loss functions
are uniformly \neq zero almost
everywhere \square

Fix: Hinge loss

For a negative training example ($y_n = -1$)



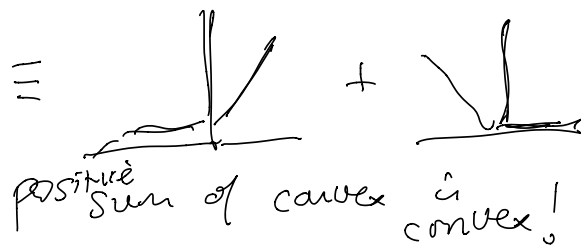
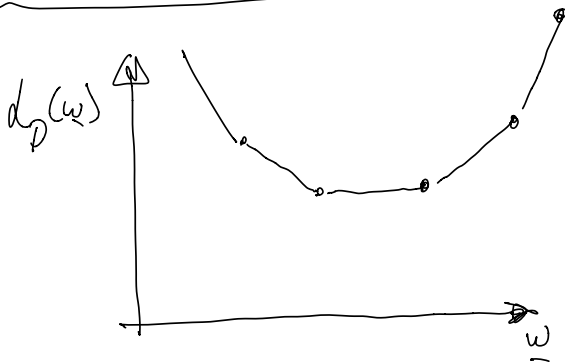
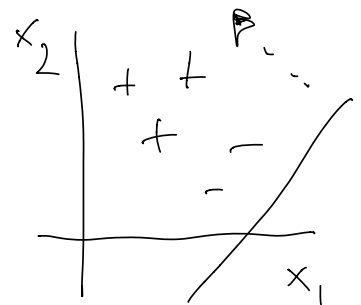
$$l_{\text{hinge}}(z) = \begin{cases} z & \text{if } z > 0 \\ 0 & \text{otherwise} \end{cases}$$

$$L_D(\underline{w}) = \sum_n l_{\text{hinge}}(-y_n(\underline{w}^T \underline{x}_n + w_0)) = \sum_{n: y_n \neq \vec{y}_n} -y_n(\underline{w}^T \underline{x}_n + w_0)$$

↳ increases with more mistakes & worse mistakes

Gradient descent can now work

L_D is Convex



Comments

+ differentiable

① Convex function can be minimized via grad descent } for small enough η

② Convex opt. is polynomial time solvable (o/ NP-hard)

Gradient descent

Repeat:

Update \underline{w} with step size $\eta \times$ gradient

$$\frac{1}{n} \sum_n \frac{\partial}{\partial \underline{w}} \ell_{\text{hinge}} \left(\frac{x_n, \underline{w}}{n} \right)$$

✓ Stable (fixed η) ^{converges for}

✗ costly per step

Stochastic gradient descent

Repeat:

Pick random minibatch $B \subseteq \mathcal{D}$ (perhaps $|B|=1$)

Update \underline{w} with step size $\eta \times$ gradient on B

$$\frac{1}{|B|} \sum_{n \in B} \frac{\partial}{\partial \underline{w}} \ell_{\text{hinge}} \left(\frac{x_n, \underline{w}}{|B|} \right)$$

✓ Faster on large data

✗ Noisy gradient

(need an adaptive learning rate ("step size") to converge; $\eta_t \propto \frac{1}{t}$)
e.g.:

Aside

* Absorbed w_0 into \underline{w} *

$$\begin{aligned}\frac{\partial}{\partial \underline{w}} h_0(\underline{w}) &= \frac{\partial}{\partial \underline{w}} \left(- \sum_{n: y_n \neq \hat{y}_n} y_n (\underline{w}^T \underline{x}_n) \right) \\ &= - \sum_{n: y_n \neq \hat{y}_n} y_n \underline{x}_n\end{aligned}$$

SGD on hinge loss ($|B|=1$)

- ① Pick (\underline{x}_n, y_n) at random
- ② If $y_n = \hat{y}$, do nothing
Else $\underline{w}_{t+1} \leftarrow \underline{w}_t + \eta y_n \underline{x}_n$

Perceptron

Rosenblatt (1958)

$$\eta = 1$$

Thm Perceptron converges if and only if data is linearly separable

Remark ①

Multi-class classification

$$y_k \in \{c_1, \dots, c_k\}$$



"All vs one"

Train k separate binary classifiers.

Classify a new example as

$$\arg \max_k h(x, w_k)$$

Remark 2

Best function!

Metrics

		True	
		0	1
Predict	0	TN	FN
	1	FP	TP

TNR
or SPEC

$$\frac{TN}{TN + FP}$$

"reject all negative?"

TPR or Recall
or SENS

$$\frac{TP}{FN + TP}$$

"find all positive?"

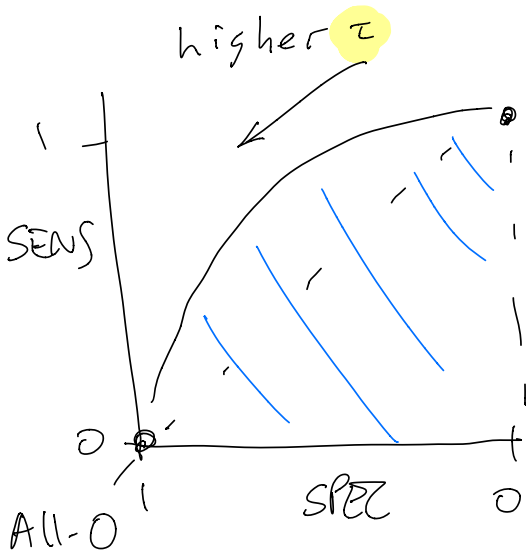
ROC curve / AUC

Classify $\hat{y} = \begin{cases} +1 & \text{if } h(\omega, x) > \text{threshold } \tau \\ -1 & \text{otherwise} \end{cases}$

new parameter



Generally we've used $\tau = 0$



"Area under curve"
 $AUC \in [0.5, 1]$
 Higher better

F1-score / Precision + Recall

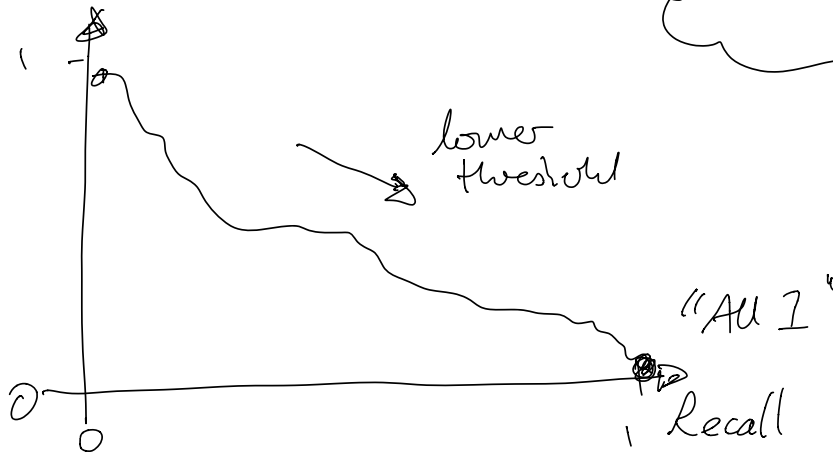
TN	FN
FP	TP

$$\left\{ \begin{array}{l} \text{PREC} \\ \frac{TP}{FP + TP} \end{array} \right\} \quad \left\{ \begin{array}{l} \text{RECALL} \\ \frac{TP}{FN + TP} \end{array} \right\}$$

$$\text{F1-score} = 2 \times \frac{P \times R}{P + R}$$

(harmonic mean)

Precision



Precision vs. recall